



# The Seven Year Leap

Updating a product from Linux 2.6 to 4.15,  
a real-world project case study

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Ed Langley, Kobilon  
[elangley@kobilon.com](mailto:elangley@kobilon.com)

# Not the first talk related to working with older kernels

- Stuck in 2009 — How I Survived  
Will Sheppard, Embedded Bits Limited  
ELCE 2016  
[https://elinux.org/ELC\\_Europe\\_2016\\_Presentations](https://elinux.org/ELC_Europe_2016_Presentations)
- How I survived to a SoC with a terrible Linux BSP  
Luca Ceresoli, AIM Sportline  
FOSDEM 2016, ELCE 2017  
[https://elinux.org/ELC\\_Europe\\_2017\\_Presentations](https://elinux.org/ELC_Europe_2017_Presentations)
- Long-Term Maintenance, or How to (Mis-)Manage Embedded Systems for 10+ Years  
Jan Lübke, Pengutronix e.K.  
ELCE 2016  
[https://elinux.org/ELC\\_Europe\\_2016\\_Presentations](https://elinux.org/ELC_Europe_2016_Presentations)

# Where are you on the kernel development spectrum?

(Or, where is your project on it?)



1: kernel maintainer

2: semiconductor/IP vendor (Initial support may go into their own repository first)

3: Recently started product/device development

4: bigger Linux distributions, (Extending to right for LTS maintenance)

5: BSP or dev kit vendor for class of devices (E.G. set top boxes)

6: Ongoing product development/maintenance (Or new one with bad BSP)

7: Legacy / heavily regulated / safety critical device maintenance

# What was the device in this project?

- Single purpose handset running Android 4.4
- Boots and loads a dedicated app written by customer app team
- HW design quite old - based on TI DM3730 (OMAP3)
  - Similar design to the BeagleBoard xM
  - Display through OMAP DSS RFBI (MIPI-DBI) -> HX8369 -> ILI9806 TFT panel
  - Other off-chip peripherals: GSM modem, Bluetooth interface

# Older kernel problems resolved

- Initial Android support using a 2.6 TI kernel
  - That kernel pre-dates addition of certain required driver features
- Backported I2C touchscreen driver
- Then had to backport OMAP3 RTC alarm wake up from suspend
  - 12 cherry picks, plus fixup to allow backported init code to run through correctly
  - Not just a case of taking a self contained .c file from a later kernel

# Older kernel problems NOT resolved

## ...and becoming blockers

- Battery life too short
  - Current draw in suspend too high: 0.09mA, needed to be 0.03mA
  - Need the SYS\_OFF\_MODE support for TWL4030 PMIC, added after 2.6
    - » Suspend/resume scripts loaded to PMIC, initialisation, OMAP HWMOD framework
    - » Would have needed to take functionality and rewrite to fit older kernel

# Older kernel problems NOT resolved

- SD card eject and re-insertion detection
  - SD card only detected and read correctly if inserted at boot
  - Expected to be trivial, was not
  - More integration with OMAP HWMOD framework
  - Again, would need significant rewrite for the very different OMAP hwmod framework in older kernel

# Older kernel problems NOT resolved

- The big one: Suspend lock up
  - When system goes into suspend, intermittently does not resume, not responsive to power button
  - Debugging the issue:
    - » Extra kernel printks, function tracing
    - » Observing current draw measurement on power supply helped characterise the issue
  - Which established:
    - » System will recover when serial port activity (Required opening handset case and soldering in wires to debug UART)
    - » More likely to occur if no touchscreen input generated after reset
    - » Very likely I2C related
  - Could have continued investigating (Had more ideas to try since)
    - » But with the other issues to deal with in the old kernel, is it worth it?



# Making the case for the upgrade

- I proposed a new kernel may solve all 3 problems at once
- Q
  - "Will it fix everything?"
  - "How long will it take? / Cost?"
- A
  - Can't promise lower power consumption, or problems fixed
  - But could try it and see...
    - » I.e. Propose least amount of effort needed to establish requirements are met / problems are fixed by a newer kernel version

# Initial plan / estimates

- To check if new kernel will resolve problems, only need to estimate work needed to check that
  - Get Linux booting to a shell prompt, kernel only needs:
    - » UART driver
    - » Existing SoC support for on-chip peripherals - to test problem areas
  - Use a plain rootfs (Not Android)
- In other projects, depending on what the problems are, getting to this point might not be so easy

# Finding the starting point

- This is probably the main area where YMMV
- For rootfs, just used buildroot
  - No BeagleBoard Yocto BSP
  - Eventual goal is Android anyway
- Newer toolchain
  - Ended up keeping older toolchain for AOSP userspace stuff
- TI DM37xx support all in mainline kernel by now
  - Should have started with that ....

# Getting to a bash prompt

```
U-Boot# bootz ${loadaddr} - ${fdtaddr}
Kernel image @ 0x80200000 [ 0x000000 - 0x50abb8 ]
## Flattened Device Tree blob at 80f80000
   Booting using the fdt blob at 0x80f80000
   Using Device Tree in place at 80f80000, end 80f9810c
```

Starting kernel ...

<nothing happens>

- First difference – where has default kernel config gone?
  - » In 2.6, for a BeagleBoard-xM built kernel with omap3\_beagle\_defconfig – long since removed
- Had several false starts trying methods to build kernel/rootfs images for a BB-xM
  - Buildroot version with extra patches for BeagleBoard
  - Kernel on BeagleBoard github
  - These had custom kernel configs or menu defaults (bb.org\_defconfig, omap2plus\_defconfig)
    - » Distracted from the correctly booting options available in mainline
- Eventual optimum setup which worked correctly:
  - Mainline kernel tree, latest stable release
  - Build with **multi\_v7\_defconfig**, then load **omap3-beagle-xm.dtb**

# Newer kernel, newer boot loader

- U-Boot support for loading a DTB
- Could have managed with older U-Boot, but path of least resistance was to upgrade U-Boot+kernel as a pair
- MLO in NAND will load U-Boot from SD if found
  - Needed to be able to load old U-Boot from newer MLO, for re-flashing old OS without opening case to press boot select button:

Default: NAND → USB → UART3 → MMC1

Boot select held: USB → UART3 → MMC1 → NAND

- After consideration, this only matters when MLO in NAND loads U-Boot from SD
- Solution was to ensure
  - U-Boot file on SD always named u-boot.bin (Same as old version)
  - New U-Boot linked to run from 0x80008000 (Again, same as old version)

# New kernel running

- Stuff that just worked out of the box:
  - Serial port
  - Power button
  - Suspend/resume
    - » Current draw in suspend now at 0.03mA
  - RTC alarm waking up from suspend
  - SD card insertion/removal detection and ability to mount

# Check the new kernel has fixed the blocking issues

- First step - ensure the point of upgrading has been achieved
- Only then move on to adding support for platform customisations/bespoke peripherals

# Check the new kernel has fixed the blocking issues

```
#!/bin/sh

LOOP_COUNT=0

echo "Suspend wake cycle test script"
echo ""

while [ true ]; do
    echo "suspending for 10 seconds"
    echo +10 > /sys/class/rtc/rtc0/wakealarm
    echo mem > /sys/power/state

    echo "woken by RTC, waiting 10 seconds"
    sleep 10

    echo ""
    echo "Iterations so far: $LOOP_COUNT"
    echo ""
    LOOP_COUNT=`expr $LOOP_COUNT + 1`
done
```



# Re-adding support for peripherals to new kernel

- First thing to remember when jumping to a present day kernel:
  - Look closely at what drivers/subsystems are about in the kernel source
  - Not everything is where you would expect it
    - » Check the `drivers/staging/` directory
  - Check DTSS of similar platforms for examples

# Example of almost doing it wrong: Backlight

- In the old kernel, the platform used a copy of backported driver:

`drivers/video/backlight/pandora_bl.c`

- With PWM channel changed
- That driver still there in 4.x
  - Started adding an altered version again, then realised that driver is leftover legacy

# Example of almost doing it wrong: Backlight

```
backlight {
    compatible = "pwm-backlight";
    pwms = <&twl_pwm 1 12000000 0>;
    pwm-names = "backlight";
    Brightness-levels = <0 5 10 15 20 25 30 35 40 45 50
                        55 60 65 70 75 80 85 90 95 100>;
    default-brightness-level = <19>; /* => 90 */
    pinctrl-names = "default";
};
```

- drivers/video/backlight/pwm\_bl.c
- drivers/pwm/pwm-twl.c

# Working with your DTS

- Just take a few moments to stop and.... learn device tree
  - As in learn how to mine through the bindings doc and identify the obscure attributes available in any given node used on your platform and so on
- <https://events.static.linuxfound.org/sites/events/files/slides/petazzoni-device-tree-dummies.pdf>

# Touchscreen

- Old kernel: `atmel_mxt_ts.c` backported
- New kernel: Atmel Maxtouch driver now in mainline
- Still needed to forward port a few alterations, E.g. for coordinate axis reversal
  - Initially tried adding `touchscreen-inverted-x/y` property to the DTS node to do this, but use of those properties are down to the driver
  - DTS bindings doc is your friend, but so is reading the source still

# Display: A bigger challenge

From drivers/video/fbdev/omap2/omapfb/dss/Kconfig:

```
config FB_OMAP2_DSS_RFBI
    bool "RFBI support"
    depends on BROKEN
    default n
    help
        MIPI DBI support (RFBI, Remote Framebuffer Interface, in Texas
        Instrument's terminology).
```

- Uh oh!
- First step: unflag as broken - got compile errors
  - Time to roll up sleeves do some proper dev work

# Re-enabled a driver... in the wrong subsystem?

- Correct long term approach would probably be to put RFBI support into:
  - `drivers/gpu/drm/omapdrm/dss/`
- For this port it was quicker to re-enable RFBI in existing location:
  - `drivers/video/fbdev/omap2/omapfb/dss/`
- Nagging awareness during this work that I was making updates in the wrong place

# Re-enabled a driver... in the wrong subsystem?

- Forward ported panel driver using HX8369+ILI9806 into:
  - `drivers/video/fbdev/omap2/omapfb/displays` (For now)
- HX83xx + ILI9xxx sounds like panel drivers which have gone into `drivers/staging/fbttft/`
  - Similar result – some of the chips variants share same interfaces (MIPI-DBI serial for example),
  - But driver plumbing in SW for TI MIPI-DBI implementation is very different to hanging a display off SPI



# RFBI being stubborn

- Driver running happily, but nothing on the screen. Checked:
  - Clocks (RFBI, DISPC, DSS)
  - Test frame output in driver, FB manual update test app
  - DISPC register values set correctly (After probe, after frame output)
  - IRQs (FRAMEDONE not triggering....)
  - Clocks again
  - Pinmuxing
  - Reset GPIO (Manually toggled, checked regs directly, check GPIO pinmux....)
  - Clocks again (Oh wait, PLL2 isn't enabled!....Still doesn't work though)
  - Reset GPIO again (Switched to using reset-gpios dts property, seemed to get that working)
  - Clocks again (Yes, really)
  - And then...

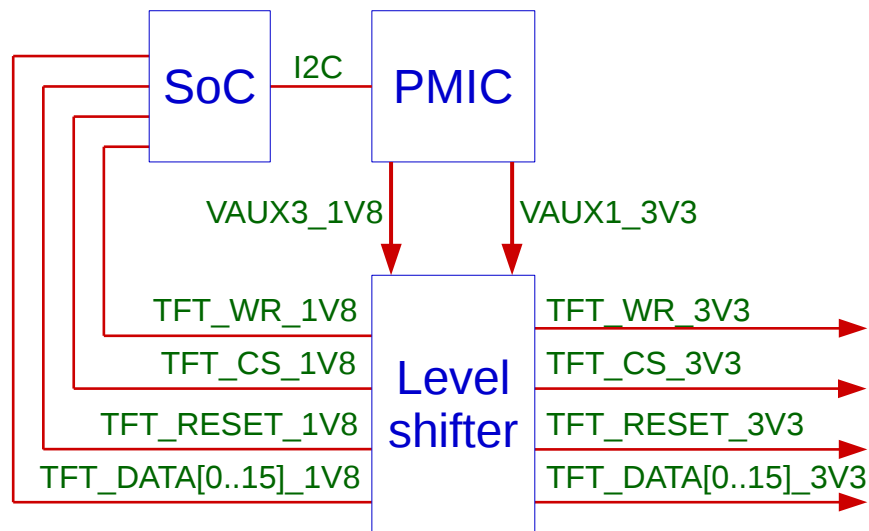
# Regulators

- Example of an item largely ignored by me in the previous kernel port

```
static struct regulator_consumer_supply beagle_vaux1_supply = {
    .supply      = "cam_3v0",
};

static struct regulator_init_data beagle_vaux1 = {
    .constraints = {
    ....
    },
    .num_consumer_supplies = 1,
    .consumer_supplies     = &beagle_vaux1_supply,
};

static struct twl4030_platform_data beagle_twldata = {
    ....
    .vaux1      = &beagle_vaux1,
    ....
};
```



# Regulators

- Which must now be enabled in a very different way

## DTS:

```
lcd0: display {  
    compatible = "ilitek,ili9806";  
    label = "lcd";  
    vcc1-supply = <&vaux1>;  
    vcc2-supply = <&vaux3>;
```

## Driver:

```
struct panel_drv_data {  
    ...  
    struct regulator *vcc1;  
};
```

## In probe():

```
ddata->vcc1 =  
    devm_regulator_get(&pdev->dev, "vcc1");
```

## In panel\_enable():

```
r = regulator_enable(ddata->vcc1);
```

# Putting Android back on again

- “Simply just replace the buildroot test rootfs with the Android filesystem images from before, right?”
- Oh yes and switch to SW rendering (Easier to ignore the GPU for now)

BoardConfig.mk:

```
USE_OPENGL_RENDERER := false
```

(Depending on Android version)

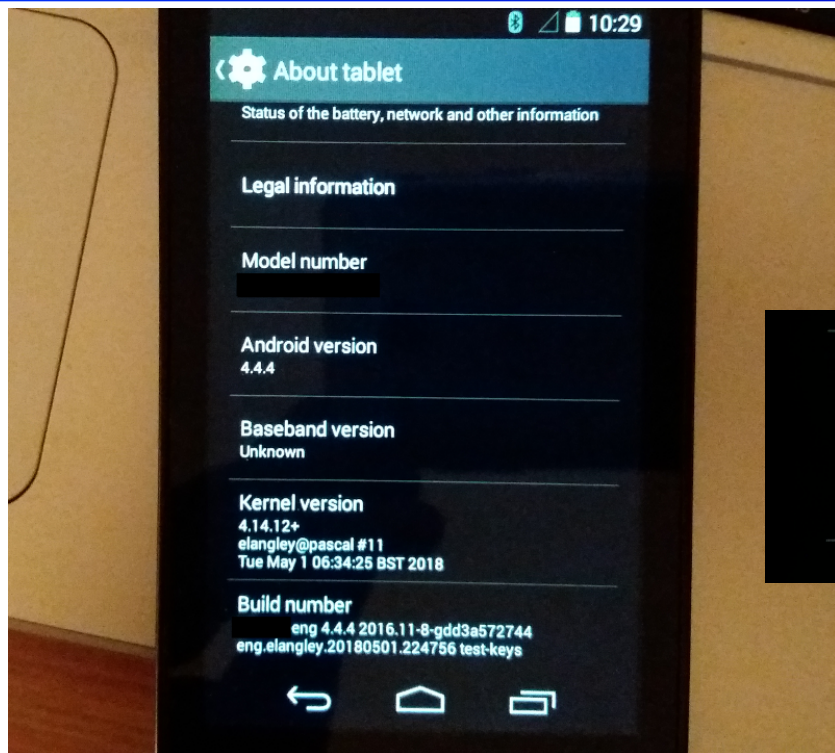
# Staying with Kitkat on 4.x kernel

- Problems:
  - ashmem driver removed
  - Android logger driver removed
  - ADB not working

# ADB support

- Android composite USB driver had been taken out
- Soon found that last available version of Android composite USB gadget driver is now very incompatible with latest kernel
- Hang on though, how does newer Android do it, after the driver was removed?
- With UBS gadget ConfigFS
  - adbd had support for that added in Android version... Kitkat (Phew)
- Re-affirmation of the lesson: Don't blindly forward port stuff, understand and leverage what is new

# First usable release

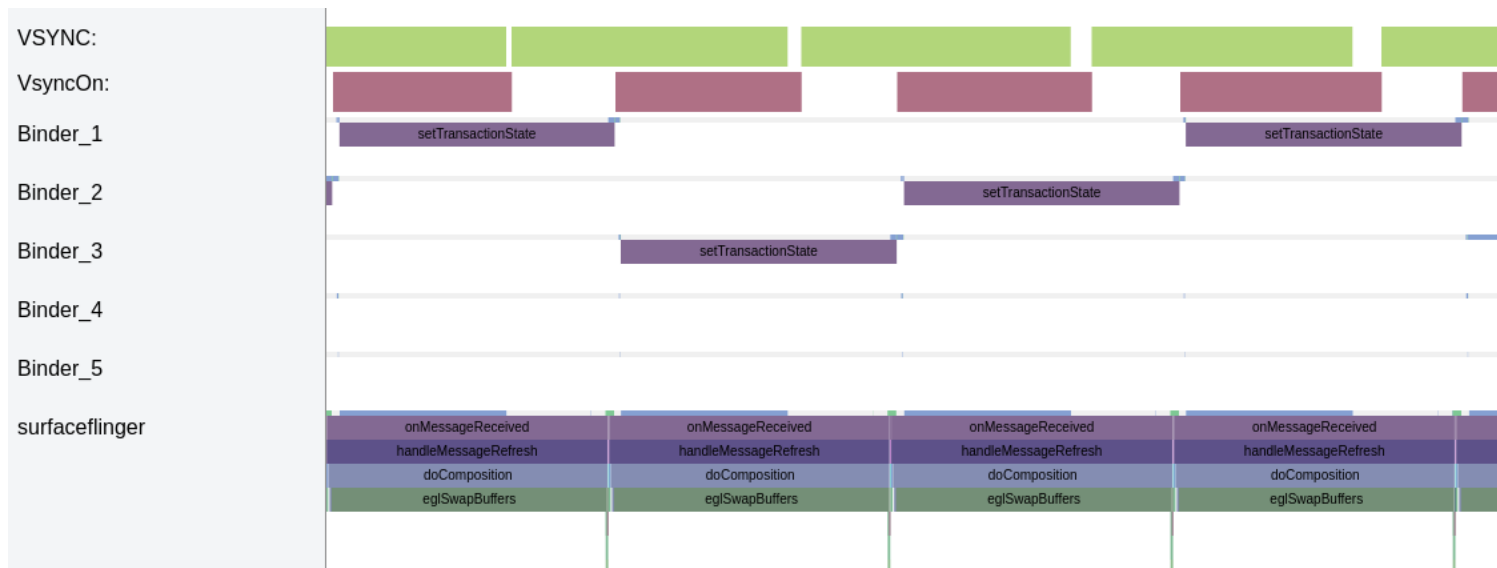


**Kernel version**  
4.14.12+  
elangley@pascal #11  
Tue May 1 06:34:25 BST 2018

Yay

# Initial feedback from test team

- "Performance is slow"
- First suspicion was the software rendering I had enabled
  - Experience of this with the platform after working on the RFBI in 2.6





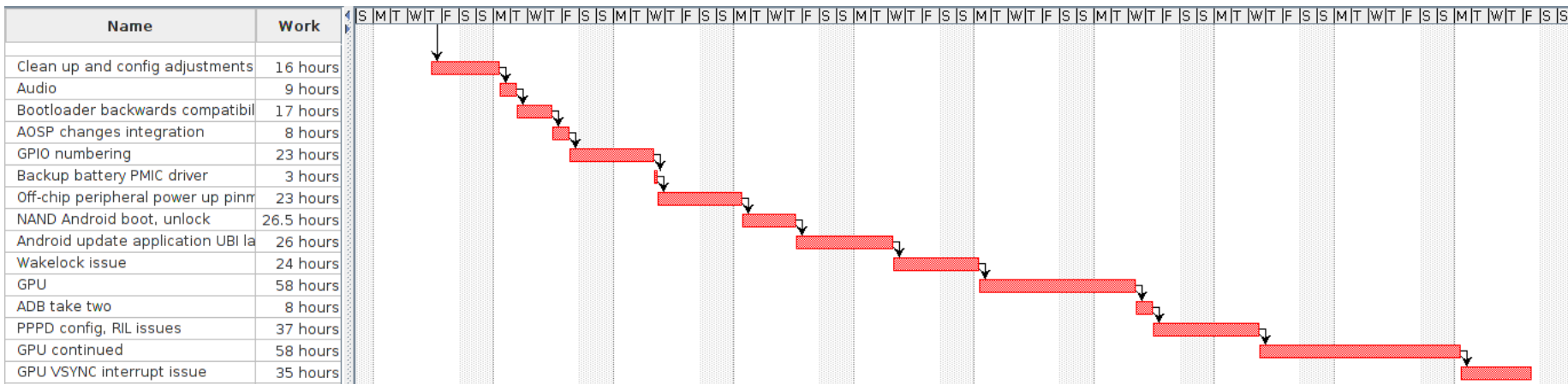
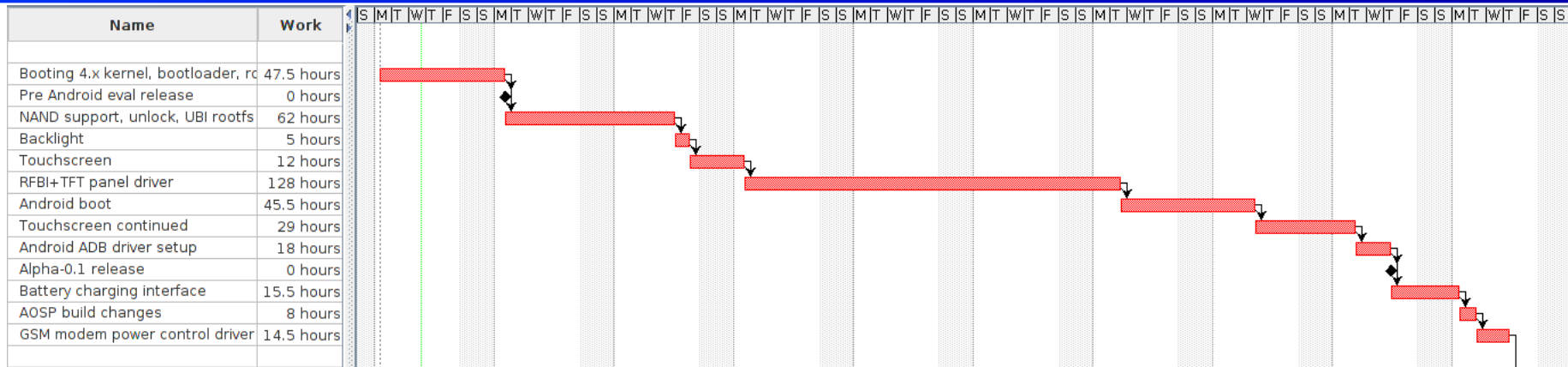
# Re-adding PowerVR SGX rendering support

- Latest version of TI Graphics SDK (5.01) only supports kernel up to 3.8
  - Forward ported pvrsvkm module to 4.14: Missing symbols on module load
  - Applied patches found online: Reset and clocking issues
  - Made further changes to enable clocks according to clock tree configuration on this platform
- That got 5.01 PVR modules + 5.01 regular SDK + 4.14 kernel working
  - Android version of TI Graphics SDK, with different EGL lib, only up to version 4.06
    - » 5.01 PVR modules + 4.06 Android SDK: PVR userspace daemon version mismatch error (against kernel driver) at init
- Eventually found a working approach by forward porting the older TI Android graphics SDK 4.06 kernel modules
  - And applying my patches

# A whole bunch of other bits

- Battery charging status / level reporting PMIC driver – update to be usable again
  - Add support for DTS properties
- Secondary battery enable and voltage reading PMIC driver
- Android OTA updater application mods for different UBI layout in NAND
- Arbitrary GPIO numbering due to enumerating each bank in random order at boot
  - Patched gpio-omap.c driver to set ordering in DTS
- ADB support take two - not working on Windows workstations (But was on Linux PC)
  - Serial number argument to gadget driver needed
  - First attempt used functionFS, Windows ADB only registers composite USB devices, made switch to configFS
  - Had to wade through Windows adb.exe source to figure those out
- GPU driver take two - VSYNC interrupt not firing

# How long did it take, in retrospect?



# How long did it take, in retrospect?

Activity	Hours	Days if 8 hours
Booting 4.x kernel, bootloader, rootfs on SD	47.5	5.9375
NAND support, unlock, UBI rootfs	62	7.75
Backlight	5	0.625
Touchscreen	12	1.5
RFBI+TFT panel driver	128	16
Android boot	45.5	5.6875
Touchscreen continued	29	3.625
Android ADB driver setup	18	2.25
Battery charging interface	15.5	1.9375

# How long did it take, in retrospect?

Activity	Hours	Days if 8 hours
AOSP build changes (kernel config, repo branches, toolchain, makefiles)	8	1
GSM modem power control driver	14.5	1.8125
Clean up and config adjustments	16	2
Audio	9	1.125
Bootloader backwards compatibility	17	2.125
AOSP changes (Init script changes etc)	8	1
GPIO numbering	23	2.875
Backup battery PMIC driver	6	0.75
Off-chip peripheral power up pinmuxing	23	2.875

# How long did it take, in retrospect?

Activity	Hours	Days if 8 hours
NAND Android boot, unlock	26.5	3.3125
Android update application UBI layout	26	3.25
Wakelock issue	24	3
GPU	58	7.25
ADB take two	8	1
PPPD config, RIL issues	37	4.625
GPU continued	58	7.25
GPU VSYNC interrupt issue	35	4.375
Totals	759.5	94.9375

# Points to remember when jumping major kernel versions

- Best starting point is to plan work needed to establish if key requirements of upgrade are met
  - Then decide to continue and plan / estimate further work after that
- Don't blindly forward port, inspect code carefully to assess:
  - What to port from old kernel
  - What to leave behind
  - What to extend in new kernel
- Check all your platform data!
  - Re-apply in DTS as appropriate
- Upstream useful changes during the project, not afterwards (Depending on certain factors)
- Every project/platform has different challenges
  - But universally something(s) always takes longer than planned

# questions?

Get in touch: [elangley@kobilon.com](mailto:elangley@kobilon.com)